Origin of temperature and field dependence of magnetic skyrmion size in ultrathin nanodots

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Understanding the physical properties of magnetic skyrmions is important for fundamental research with the aim to develop new spintronic device paradigms where both logic and memory can be integrated at the same level. Here, we show a universal model based on the micromagnetic formalism that can be used to study skyrmion stability as a function of magnetic field and temperature. We consider ultrathin, circular ferromagnetic magnetic dots. Our results show that magnetic skyrmions with a small radius—compared to the dot radius—are always metastable, while large radius skyrmions form a stable ground state. The change of energy profile determines the weak (strong) size dependence of the metastable (stable) skyrmion as a function of temperature and/or field.

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Nonlinear localized excitations have attracted the attention of physicists for a long time. Such excitations, including solitary waves or solitons, play an important role in optics, quantum field theory, condensed matter, and other fields. It is sometimes possible to associate integer numbers (topological charges) to the solitons, which are preserved in their dynamics. Topologically nontrivial magnetization configurations in ferromagnets, such as domain walls, vortices, and skyrmions are currently the focus of a lot of research activity. These spin textures are also candidates for nanoscale device applications—computational paradigms, magnetic storage, and programmable logic—due to their small size [1–13].

Skyrmion solutions were obtained first by Skyrme in the nonlinear field theory [14]. Subsequently chiral skyrmions were predicted [15], and discovered experimentally in noncentrosymmetric cubic B20 compounds [16-20] which permit an antisymmetric anisotropic interaction, namely, the Dzyaloshinskii-Moriya interaction (DMI). This arises from a relativistic correction and relies on spin-orbit interactions [21,22]. Recent efforts have focused on materials with interfacial DMI—especially ultrathin transition-metal/heavy-metal multilayers with large spin-orbit coupling such as Co/Pt and Co/Ir [8,23,24]. The DMI is necessary to yield axisymmetric skyrmions in ultrathin magnetic elements and the chiral skyrmions can be further stabilized by an external magnetic field [8,23,24]. Temperature is usually considered to be detrimental to skyrmion stability, leading to either the transformation of the skyrmion state into a more energetically favorable state [25] or to nucleation of multiple skyrmions and labyrinth domains [8,23,24]. In addition, recent room-temperature experiments with an external out-of-plane magnetic field [8,23], showed a strong nonlinear dependence of the skyrmion radius on the external field strength pointing out the key role of the external field.

Rohart and Thiaville [26] developed a domain-wall model of Néel skyrmions at zero temperature T and zero magnetic field $H_{\rm ext}$, and identified a critical DMI parameter D_c quantifying the influence of DMI that is independent of the dot size. They found that the skyrmion radius $R_{\rm sk}$ diverges as the DMI parameter $D \rightarrow D_c$. In a finite magnetic dot, however, $R_{\rm sk}$ is determined by the confining potential and cannot exceed the dot radius R_d [26]. This analytical model yields incorrect results for $D > D_c$ and should be improved.

The temperature dependence of the skyrmion radius in an infinite film was calculated numerically by Barker and Tretiakov [27] who attempted to use Rohart's expression for $R_{\rm sk}$ with the temperature dependence of the magnetic properties of the host material to explain the behavior. In that paper [27], no temperature dependence of D was considered. The authors concluded that in ferromagnets the skyrmion radius has a weak quasilinear temperature dependence. This is rather a result of using the equation by Rohart $et\ al.$ for small radius (\sim 10 nm) skyrmions which have a size comparable with the domain-wall width.

Our work is motivated by the lack of understanding regarding the skyrmion size and stability as a function of control parameters such as temperature and external field in a finite-size sample.

Here, we provide a simple analytic tool for identifying materials and geometries which can host skyrmions in a target temperature and field window. Particularly, the analytical model predicts weak/strong dependence of skyrmion size on control parameters which is further confirmed by numerical

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modeling. More in detail, we present a theoretical approach to skyrmion stability based on minimization of the magnetic energy using a skyrmion ansatz in confined geometries. We show that the thermal evolution of skyrmion size in ultrathin dots is best expressed in a Q-d phase space of the skyrmion quality factor $Q = 2K_u/\mu_0 M_s^2$ (K_u is the uniaxial anisotropy constant, M_s is the saturation magnetization, μ_0 is the vacuum permeability), and the reduced DMI strength $d = |D|l_{\rm ex}/A$ $(l_{\rm ex} = \sqrt{2A/\mu_0 M_{\rm s}^2})$ is the exchange length, with A being the exchange constant). The proximity of the point describing the skyrmion state in this Q-d phase space, to the border of the skyrmion stability, is the crucial parameter in understanding the linear or nonlinear change in radius with temperature or field as observed in micromagnetic simulations. The temperature dependence of the skyrmion stability is expressed as scaling relations of both Q and d with changing the reduced magnetization $m(T) = M_s(T)/M_s(0)$. We find the equilibrium skyrmion size increases rapidly with temperature only when approaching a critical line $d_c(Q) = (4/\pi)\sqrt{Q-1}$. The size becomes comparable with the dot radius at $d(T) > d_c(T)$. The metastable skyrmions have small radius $(R_{sk} \ll R_d)$, whereas the stable (ground state) ones have large radius. The out-of-plane external magnetic field can be used to bring metastable skyrmions closer to or farther from the critical line $d_c(Q)$ where the metastable skyrmion becomes a ground-state skyrmion.

The magnetic skyrmion can be described by the energy functional $E[\mathbf{m}] = \int dV \, \varepsilon(\mathbf{m})$, with the energy density

$$\varepsilon(\mathbf{m}) = A(\nabla \mathbf{m})^2 + \varepsilon_{\text{DMI}} + K_u m_z^2 -0.5 M_s \mathbf{m} \cdot \mathbf{H}_m - M_s \mathbf{m} \cdot \mathbf{H}_{\text{ext}}, \tag{1}$$

where $\mathbf{m} = \mathbf{M}/M_s$ is the unit magnetization vector $\varepsilon_{\mathrm{DMI}} = D[m_z(\nabla \cdot \mathbf{m}) - (\mathbf{m} \cdot \nabla)m_z]$ is the interface DMI energy density, m_z is the magnetization z component, \mathbf{H}_m is the magnetostatic field, and $\mathbf{H}_{\mathrm{ext}}$ is the external magnetic field.

We assume that in an ultrathin circular dot the magnetization \mathbf{m} does not depend on the thickness (z coordinate). We introduce polar coordinates in the dot plane $\rho = (\rho, \phi)$, and define spherical angles of the magnetization vector (Θ, Φ) as functions of ρ . We also assume that the static skyrmion centered in the dot is axially symmetric and use the equations $\Theta_0(\rho) = \Theta_0(\rho), \Phi_0(\rho) = \phi + \phi_0$. In seeking a general expression for the dependence of the skyrmion size on both temperature and external magnetic field, and to overcome drawbacks of previous approaches in estimating the skyrmion radius [28] (see note 1 in the Supplemental Material), we developed an analytical approach using a different skyrmion ansatz from Refs. [26,29]. To minimize the energy functional (1), we propose the trial function

$$\tan\frac{\Theta_0(r)}{2} = \frac{r_{\rm sk}}{r} e^{\xi(r_{\rm sk} - r)},\tag{2}$$

where $r=\rho/l_{\rm ex}$, $\xi^2=Q-1$, and the polar angle Θ_0 describes the static skyrmion profile. The accuracy of the ansatz (2) was numerically verified in the case of two-dimensional easy axis infinite ferromagnets (Q>1) in Ref. [30]. Equation (2) recovers the Belavin-Polyakov solution for the isotropic case $\xi=0$ and leads to the finite exchange energy at $r\approx0$. Equation (2) is also very similar (in the area of its applicability, at $r\approx r_{\rm sk}\gg1$) to

the ansatz used in the theory of bubble domains [31] in highly anisotropic ferromagnetic films [28] (see approach 3 in note 1 in the Supplemental Material).

The energy E and the equilibrium skyrmion radius $r_{\rm sk} =$ $R_{\rm sk}/l_{\rm ex}$ can now be expressed as functions $E[r_{\rm sk},Q,d,H_{\rm ext}]$ and $r_{\rm sk}[Q,d,H_{\rm ext}]$. The conditions of the skyrmion stability can be found using a standard variational procedure, solving the equations $\partial E/\partial r_{\rm sk} = 0$, $\partial^2 E/\partial r_{\rm sk}^2 = 0$. To account for the temperature dependence of the skyrmion radius, we use the scaling approach for macroscopic (micromagnetic) parameters which usually decrease with temperature increasing due to the magnetization fluctuation effects. Including thermal effects into a micromagnetic approach is known to largely overestimate the Curie temperature as compared to the more accurate atomistic approach [32]. However, the largest temperatures considered in the present study are very far from the Curie temperature $(T/T_c < 1/2)$. In this case, the micromagnetic approach produces accurate results in terms of the thermodynamically averaged quantities as a function of the magnetization m(T). We calculated the temperature dependence of uniaxial magnetic anisotropy $K_u(T) = K_u(0)m(T)^{\gamma}$ achieving $\gamma = 3.03$ that is close to the Callen-Callen relation [33]. The scaling of the exchange $A(m) = A(0)m^{\alpha}$ and DMI $D(T) = D(0)m(T)^{\beta}$ parameters is found by atomistic simulations of an infinite thin film calculating the thermal spin-wave spectrum [34,35] and fitting the long-wavelength regime (small k vectors) with a linear spin-wave theory [28] (see note 2 in the Supplemental Material). We obtain $\alpha = \beta = 1.5$, consistent with other recent results [36,37].

To benchmark the theory, we consider a circular nanodot (e.g., Co) of diameter $2R_d=400$ nm and thickness of 0.8 nm assumed to be in contact with a thin layer of heavy metal (e.g., Pt) giving an appreciable interfacial DMI. We performed systematic micromagnetic simulations to calculate the skyrmion size as a function of the out-of-plane external field $H_{\rm ext}$ (from 0 to 50 mT) and temperature (from 0 to 300 K) integrating the Landau-Lifshitz-Gilbert equation of motion for the reduced magnetization $\mathbf{m} = \mathbf{M}/M_s$ [28,38–42] (see note 3 in the Supplemental Material). At T=0 K, we used the following material parameters: $M_s=600$ kA/m [8], A=20 pJ/m [43], D=3.0 mJ/m² [44,45], $K_u=0.60$ MJ/m³ [8], and Gilbert damping $\alpha_G=0.1$ [46]. As a reference, Rohart's critical DMI value $D_C=3.48$ mJ/m² for our parameters at T=0 K [26].

Temperature causes the skyrmion to diffuse and leads to fluctuations of the diameter and deformations of the skyrmion shape [27,47,48], losing the circular symmetry. We therefore calculated the effective diameter by assuming that the area of the skyrmion core (here it is the region where the z component of the magnetization is negative) is equivalent to a circle [27]. The skyrmion diameter and perimeter display approximately Gaussian statistical distributions [28] (see note 3 in the Supplemental Material) with increasing widths with temperature.

Figure 1(a) compares the magnetic field dependence of the skyrmion diameter calculated by micromagnetic simulations with the analytic skyrmion ansatz, Eq. (2), at $T=0\,\mathrm{K}$. There is a reasonably good agreement considering there are no fitting parameters (maximum difference around 8% at zero field). Figure 1(b) shows the temperature dependence of the skyrmion diameter calculated with micromagnetic simulations

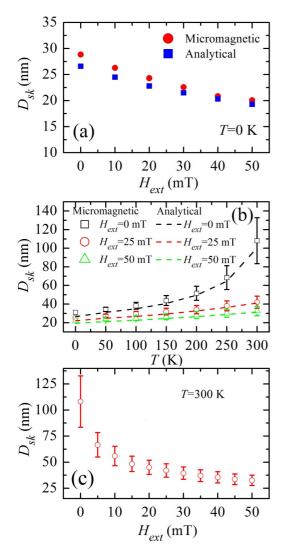


FIG. 1. (a) Skyrmion diameter as a function of the perpendicular external field as computed by micromagnetic simulations (red circles) and by analytical computations based on Eq. (2) (blue squares) at $T=0\,\mathrm{K}$. (b) Skyrmion diameter as a function of temperature for three values of the perpendicular external field. The symbols represent the mean value of the skyrmion diameter as obtained by micromagnetic simulations including thermal fluctuations, where the error bar corresponds to the standard deviation, while the dashed curves are related to the analytical results with scaled values of the macroscopic parameters, using $\alpha=1.50,\ \beta=1.50,\ \mathrm{and}\ \gamma=3.585.\ \gamma$ is approximately 15% larger than the one derived from atomistic simulations [33]. (c) Mean value of the skyrmion diameter and corresponding standard deviation as error bar as a function of applied external field for $T=300\,\mathrm{K}$, calculated from micromagnetic simulations.

for three values of the external field (open symbols). At zero field, the skyrmion diameter rapidly expands with increasing temperature. The increasing out-of-plane field causes a weak quasilinear increasing of the diameter up to $T=300\,\mathrm{K}$ [red circles and green triangles in Fig. 1(b)]. Our computations show that two thermal/field regimes exist: at high temperature ($T>200\,\mathrm{K}$) and low field ($H_{\rm ext}<10\,\mathrm{mT}$), the skyrmion size is strongly influenced by thermal fluctuations, whereas at

low temperature ($T \le 200 \,\mathrm{K}$) independent of the field, or at high temperature and high field ($H_{\mathrm{ext}} \ge 10 \,\mathrm{mT}$), the skyrmion is weakly affected by thermal fluctuations. These different behaviors were not observed in Ref. [27], because with the parameters used, the skyrmions were always in the metastable region. When calculating the skyrmion diameter as a function of the external field for $T = 300 \,\mathrm{K}$ [Fig. 1(c)], there is a large, nonlinear expansion of the diameter and larger variance as the external field is reduced. This is consistent with the experimental results in Refs. [8,23].

By including the scaling relations in the analytical approach, the results are in agreement with micromagnetic simulations until the skyrmion is in the metastable region far from the boundary of the stable region [28] (e.g., when $T < 200 \,\mathrm{K}$ for $H_{\mathrm{ext}} = 0 \,\mathrm{mT}$; see note 3 in the Supplemental Material). When approaching the ground-state region, the confining potential—due to the magnetostatic field and the DMI boundary conditions—starts to play a significant role in fixing the skyrmion size [11,26]. To account for this, we consider the scaling exponent γ of the uniaxial perpendicular anisotropy $K_u(T) = K_u(0)m(T)^{\gamma}$ as a fitting parameter. This is because the analytical model is developed within the thin-film approximation where the effective anisotropy is computed as $K_{\text{eff}}(T) = K_u(T) - 0.5\mu_0 M_s(T)^2$, but the numerical micromagnetic solution includes the full magnetostatic calculation. By performing athermal (deterministic) micromagnetic simulations [28] (see note 3 in the Supplemental Material), an excellent agreement is found for $\gamma = 3.585$. With this value, we can calculate the skyrmion diameter dependence on temperature and field by Eq. (2) [dashed lines in Fig. 1(b)]. The analytical [ansatz Eq. (2)] and micromagnetic results agree well and we conclude that our analytical expression is accurate in predicting the skyrmion size for arbitrary temperature and external field combinations.

Figure 1(c) shows how even a small external field strength $H_{\rm ext} = 5 \, \rm mT$ significantly reduces the skyrmion size at room temperature. This occurs because the magnetization region outside of the skyrmion core expands—the field direction is opposite to the skyrmion core magnetization—leading to a shrinking of the skyrmion. The nonlinear field–skyrmion size dependence is in qualitative agreement with recent experimental results (see, for comparison, Fig. 4a in Ref. [23] and Fig. S8 in the Supplemental Material of Ref. [8]).

To understand the origin of the two thermal/field regimes, we focus on the data obtained at zero external field. We calculate the critical DMI parameter for each set of the scaled parameters by the expression $D_c(T) = 4\sqrt{A(T)K_{\rm eff}(T)}/\pi$ [26]. When D approaches D_c (as temperature increases; see Fig. 2), a sharp increase of the skyrmion size $R_{\rm sk}(T)$ occurs [26]. This could explain why, at room temperature, the skyrmion size increases for $H_{\rm ext} < 5$ mT exhibiting a nonlinear dependence on the external field [8,23] [see Fig. 1(c)].

The thermal scaling of the macroscopic parameters leads to the temperature dependence of the quality factor $Q(T) = Q(0)m(T)^{\gamma}$. Taking into account the definition $d(T) = D(T)l_{\rm ex}(T)/A(T)$, we derive the temperature dependence of the reduced DMI parameter as $d(T) = d(0)[m(T)]^{\beta-\alpha/2-1}$. Note that temperature dependence of the reduced critical DMI parameter $d_c(m) \propto m^{-1} \sqrt{K_{\rm eff}(m)} \propto \sqrt{Q(m)-1}$ includes neither the exchange stiffness α nor the DMI exponent

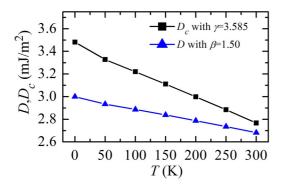


FIG. 2. Comparison of temperature dependences of the scaled DMI parameter D and the scaled critical DMI parameter D_c when $H_{\text{ext}} = 0 \,\text{mT}$.

 β . This justifies the use of the skyrmion stability diagram expressed in the reduced coordinates, Q and d, presented in Fig. 3(a). The parameters at T=0 K are Q(0)=2.65, d(0)=1.41, and $l_{\rm ex}(0)=9.4$ nm [the scaling law for the reduced DMI parameter is $d(m) \propto m^{\beta-\alpha/2-1}$, i.e., $d(m) \propto m^{-0.84}$). The dependence d(m) determines the evolution of the point describing the skyrmion configuration in the Q-d plane accounting for the change of temperature via the m(T) law [Fig. 3(a)]. The increase of parameter d leads to the stabilization of the skyrmion state and a rapid expansion of the skyrmion radius. This effect is especially strong at $H_{\rm ext}=0$ mT. A finite value of the field $H_{\rm ext}$, opposing the skyrmion core magnetization, results in a contraction of the skyrmion radius and the skyrmion radius weakly increases with T. In other words, the skyrmion

radius increase is suppressed by the finite magnetic field which does not occur at zero field.

There are two qualitatively different behaviors of how the skyrmion radius $R_{\rm sk}(T)$ changes with temperature at $H_{\rm ext} = 0$ mT according to the parameters Q and d:

- (1) The skyrmion radius $R_{\rm sk}(T)$ is an almost constant function of temperature when the skyrmion configuration remains in the metastable region.
- (2) The skyrmion radius $R_{\rm sk}(T)$ increases sharply with increasing temperature when approaching the region of skyrmion ground-state stability.

The first scenario is realized when the T=0 K parameters Q(0), d(0), and $l_{\rm ex}(0)$ correspond to the skyrmion metastable state [Figs. 3(a) and 3(c)]. In this case, the skyrmion radius at T=0 K is small and has only a weak temperature dependence $R_{\rm sk}(T)$ up to 200 K because the skyrmion is deep in the region of metastability in the Q-d phase diagram. The decreasing function d(m) guarantees that the skyrmion state stays in the (Q,d) area of the skyrmion metastability for increasing temperature.

The second behavior occurs when a skyrmion, initially in the metastable state with parameters Q(0), d(0), and $l_{\rm ex}(0)$ [see Figs. 3(a) and 3(b)], moves toward the area of global stability in the Q-d space. This is realized for our dot magnetic parameters from $T=200\,\mathrm{K}$ to $T=350\,\mathrm{K}$ [green points in Fig. 3(a)]. In this case, the skyrmion radius at $T=0\,\mathrm{K}$ is small, but it shows a strong dependence with increasing temperature $R_{\rm sk}(T)$.

For further increasing of T up to 400 K, the skyrmion reaches the area of its stability [magenta point in Fig. 3(a)] crossing the uniform state–skyrmion equilibrium line [red dashed line in Fig. 3(a)]. At this line the skyrmion energy is equal to the perpendicular uniform state energy, $d = d_c$;

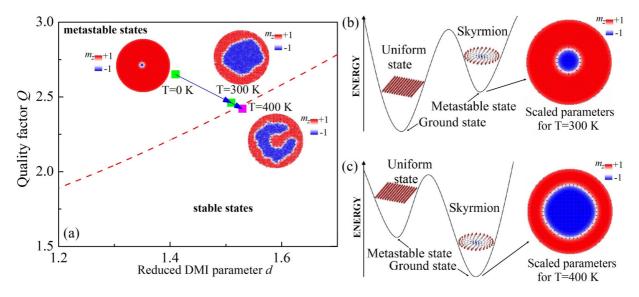


FIG. 3. (a) Q-d skyrmion stability diagram for $H_{\rm ext}=0$ mT. The green squares indicate the metastable skyrmion states at T=0 K and T=300 K, while the magenta square indicates the stable skyrmion state at T=400 K obtained with our parameters. The dashed red line represents the critical DMI parameter D_c as defined in Ref. [26]. The blue arrows indicate how the state evolves as a function of temperature. Insets: example of spatial distributions of the magnetization at T=0, 300, and 400 K. Sketch of the energy profile of the dot when the skyrmion corresponds to (b) a metastable state and (c) when it occupies an absolute energy minimum (ground state). Two spatial distributions of the magnetization shown in (b) and (c) refer to deterministic full micromagnetic simulations with scaled values of the parameters for T=300 K and T=400 K, respectively. For all the spatial distributions of the magnetization, a color scale linked to the normalized z component of the magnetization is also illustrated.

the skyrmion radius is large and depends on the confining potential. In particular, the skyrmion radius calculated from deterministic micromagnetic simulations with scaled values of the parameters (corresponding to $T=400\,\mathrm{K}$) is much larger than the skyrmion radius for $T=300\,\mathrm{K}$ [compare the spatial distribution of the magnetization in Fig. 3(b) with that in Fig. 3(c)]. In the region of stability where the skyrmion is the ground state of the ferromagnet, the ratio $R_{\rm sk}/R$ is a weak function of all parameters.

On the other hand, when considering in the micromagnetic simulations thermal fluctuations at $T=400\,\mathrm{K}$, we observe large deformations of the skyrmion which turn into a "horseshoe"-like configuration as already observed in experiments [8], while it remains quasicircular for $T=300\,\mathrm{K}$ [see insets in Fig. 3(a)]. Here we do not consider stabilization of multiple skyrmions or labyrinth domain textures, assuming that the parameter d is not very large and we are always in the area of the single skyrmion stability.

From a technological point of view, understanding how to move skyrmions between the metastability and the confined ground state can be exploited to enhance the electrical skyrmion detection [48] (see note 4 in the Supplemental Material and Supplemental Material Video 1 [28]).

In summary, we developed a theoretical framework describing the skyrmion stability in ultrathin dots as a function of the external magnetic field and temperature by combining a proper ansatz with thermal scaling relations of the micromagnetic parameters A, K_u , and D obtained by atomistic spin dynamics (although this direct estimation can be time-consuming, the scaling exponents can be alternatively retrieved from

experimental measurements). We showed that the strong temperature dependence of the skyrmion diameter occurs because the thermal evolution of an initially metastable skyrmion brings it toward the region where the skyrmion is the ground state due to an increase of the effective DMI strength in comparison to the anisotropy. Our results, corroborated by extensive micromagnetic simulations, provide a tool, the *Q-d* phase diagram, to determine the transition from the metastable to ground-state skyrmion configuration, as well as the skyrmion size in the presence of both out-of-plane external field and temperature. Our achievements could be beneficial for racetrack memories where localized manipulation of magnetic parameters can be used to vary the skyrmion size and stability, improving the ability for skyrmion electrical detection.

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SUPPLEMENTARY INFORMATION

Origin of temperature and field dependence of magnetic skyrmion size in ultrathin nanodots

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We assume that in an ultrathin circular dot with thickness t about 1 nm and radius R_d , the magnetization \mathbf{m} does not depend on the thickness (z-coordinate). We introduce the polar coordinates in the dot plane $\mathbf{\rho} = (\rho, \phi)$, and define spherical angles of the magnetization vector (Θ, Φ) as functions of $\mathbf{\rho}$. We also assume that the magnetization of the static skyrmion centered in the dot is circularly symmetric and use the equations $\Theta_0(\mathbf{\rho}) = \Theta_0(\rho)$, $\Phi_0(\mathbf{\rho}) = \phi + \phi_0$. The DMI energy depends on the product of the DMI parameter D and skyrmion chirality $C = sign(m_\rho) = \cos \phi_0$ demanding $\phi_0 = 0$, π (Néel skyrmions) and CD = -|D| < 0. The energy of the face magnetic charges is accounted via the effective uniaxial anisotropy $K_{eff} = K_u - \mu_0 M_s^2 / 2$. The magnetostatic energy of the volume and side surface charges is neglected due to small dot thickness.

The polar angle Θ_0 , describing the static skyrmion profile, satisfies the equilibrium equation obtained from the minimization of the energy functional:

$$\nabla^2 \Theta_0 = \left(\xi^2 + \frac{1}{r^2}\right) \sin \Theta_0 \cos \Theta_0 - \frac{d}{r} \sin^2 \Theta_0 + h \sin \Theta_0, \qquad (S1)$$

where $\xi^2 = Q - 1 = 2K_u/\mu_0 M_s^2 - 1$ describes the effective easy-axis magnetic anisotropy, $h = H_{ext}/M_s$ is reduced perpendicular magnetic field, $r = \rho/l_{ex}$, and $d = |D|l_{ex}/A$ $(l_{ex} = \sqrt{2A/\mu_0 M_s^2})$ is the exchange length). The non-linear differential Eq. (S1) should be complemented by the boundary conditions $\Theta_0(0) = \pi$ or 0 (i.e., $m_z = -1$ or +1), $\Theta_0(r_{sk}) = \pi/2$ and $\partial\Theta_0/\partial r = d/2$ at $r = R_d/l_{ex}$ [1]. Here $r_{sk} = R_{sk}/l_{ex}$ is the reduced skyrmion radius defined as $m_z(r_{sk}) = 0$.

In order to obtain the skyrmion radius dependence on field and temperature, we can consider three state-of-the-art approaches. The first one solves Eq. (S1) in some limiting case, while the other two minimize the energy functional (Eq. (1) in the main text) using different trial functions.

Approach 1.

Eq. (S1) has a simple analytical solution only for the dominating isotropic exchange interaction (Q=1, d=0), $\tan(\Theta_0(r)/2) = r_{sk}/r$, which is known as Belavin-Polyakov (BP) soliton.

We use the definite skyrmion polarization p=-1 defined as the z-component of the magnetization in the skyrmion center, $p = \cos \Theta_0(0)$.

Approach 2.

The simplest trial function widely used in the domain wall theory is the linear ansatz $(\Theta_0(\rho) = \pi(1-\rho/2R_{sk}))$ at $\rho \leq R_{sk}$, $\Theta_0(\rho) = 0$ at $\rho \geq 2R_{sk}$ [2]. The equilibrium skyrmion radius derived from the linear ansatz is directly proportional to the DMI constant

$$R_{sk} (H_{ext}) = \frac{D}{4M_s^2 \left[Q - 1 + \frac{1}{\pi} \left(1 - \frac{4}{\pi^2} \right) \frac{H_{ext}}{M_s} \right]},$$
 (S2)

where the perpendicular field $H_{\rm ext}$ is opposite to the skyrmion core magnetization.

It can be shown that the skyrmion radius given by Eq. (S2) can describe neither the field dependence obtained by micromagnetic simulations and experimental measurements at room temperature, nor the simulated temperature dependence of the skyrmion radius at zero field. The field and temperature dependence of the skyrmion radius given by Eq. (S2) exhibits a different slope in comparison with obtained by micromagnetic simulations (see Fig. S1) and measured experimentally. In addition, the drawbacks of the linear ansatz are: 1) it predicts that the chiral skyrmion is metastable at any |D| > 0 (the critical value of DMI $D_c = 0$) and any Q > 1, the skyrmion cannot be the dot ground state; 2) the area of the skyrmion metastability (|D| > 0, Q > 1) does not depend on the exchange constant A for small radius skyrmions, $R_{sk} / R \le 1/2$; 3) the dependence of the skyrmion radius $R_c(D)$ calculated within the ansatz is linear in D, whereas this function is strongly non-linear with an inflation point at $D \approx D_c$ (with a finite D_c) as also shown numerically in Ref. [1].

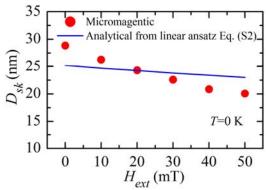


FIG. S1: Skyrmion diameter as a function of the perpendicular external field as computed by micromagnetic simulations (red circles) and by analytical computations based on the linear ansatz in Eq. (S2) (blue curve) at T=0 K.

Approach 3.

We can choose the following ansatz describing a circular domain wall:

$$\tan\frac{\Theta_0(\rho)}{2} = e^{p\frac{(\rho - R_{sk})}{\Delta}}$$
 (S3)

where $\Delta = \sqrt{A/K_{eff}}$ is the domain wall width.

Eq. (S3) is a very good approximation within the limit $R_{sk} >> \Delta$. However, in our case, $R_{sk}/\Delta \approx 2$ only, and then Eq. (S3) has a bad accuracy and cannot be applied. Moreover, the ansatz (S3) leads to a singularity in the exchange energy at $\rho \to 0$, because it does not satisfy the boundary condition $\Theta_0(0) = \pi$. Substituting the ansatz (S3) to the magnetic energy functional (Eq. (1) in the main text), and conducting integration in the vicinity of $\rho \approx R_{sk}$, the equilibrium skyrmion radius of Ref. [1] is obtained

$$R_{sk} = \frac{\Delta}{\sqrt{2\left(1 - D/D_c\right)}},\tag{S4}$$

Eq. (S4) is applicable in a narrow region at $D < D_c$, when the skyrmion is metastable/unstable. Other drawback of Eq. (S4) is a prediction of such a small value of $R_{sk} \approx \Delta$, for which the ansatz (S3) cannot be applied.

Therefore, the form of the approximate solution for the skyrmion equilibrium radius R_{sk} depends on the relative value of the ratio $\zeta = R_{sk}/\Delta$:

- 1) The Belavin-Polyakov model is approximately valid at $\zeta \le 1$ (small radius skyrmion);
- 2) The linear $\Theta_0(\rho)$ model and Eq. (S2) are valid for intermediate $1 < \varsigma \le 5$ (however, it has other drawbacks);
- 3) The domain wall ansatz (S3) is valid for large R_{sk} , $\varsigma > 5$.

The temperature dependence of macroscopic magnetic parameters, such as m(T) and $K_u(T)$, can be calculated from a microscopic formalism. This formalism includes spin fluctuations which cause the macroscopic magnetization to change length and the magnetic parameters to decrease as the system samples larger areas of the free energy [3].

We used atomistic spin dynamics (ASD) to calculate the temperature dependence of A(T), $K_u(T)$ and D(T) from the finite temperature spin wave spectrum. Temperature is included in the classical (white noise) limit and general details of the method can be found in Ref. [4]. We consider a 2D simple cubic thin film in the x-y plane, as was used in the micromagnetic calculations. The Hamiltonian is:

$$H = -J\sum_{\langle ij \rangle} \mathbf{S_i} \cdot \mathbf{S_j} + \sum_{\langle ij \rangle} d\left(u_{ij} \times \hat{z}\right) \cdot \left(\mathbf{S_i} \times \mathbf{S_j}\right) - \mu_s \sum_{i} \mathbf{B} \cdot \mathbf{S_i} \quad , \tag{S5}$$

where S_i are classical spins of unit length, $J = 1.0 \cdot 10^{-20}$ and $d = 6.0 \cdot 10^{-22}$ Joules, and $\mu_S = 1.62 \,\mu_B$ corresponding to the micromagnetic parameters with the unit cell sizes a = 0.25 nm and c = 0.4 nm. The angle brackets $\langle ij \rangle$ indicate a summation over nearest neighbors only. We use a large magnetic field $H_{ext} = (0, 10T, 0)$ to force the magnetization to lie in the plane of the film while also maintaining a uniform texture. The DMI manifests as a k-shift of the spin wave frequency. The system size is 256x256x1 unit cells, i.e., we conduct simulations in the 2D limit and with a large inplane size to reduce finite size effects. Periodic boundary conditions are used in the x-y directions.

The dynamics are solved using the Landau-Lifshitz-Gilbert equation for each spin using the Heun method with the Gilbert damping α_G =0.001 and Δt =1 fs.

The finite temperature spin wave spectrum is calculated from the space-time Fourier transform of the S_x , S_y spin component fluctuations (following the same procedure as in Ref. [5]) giving the result in Fig. S2.

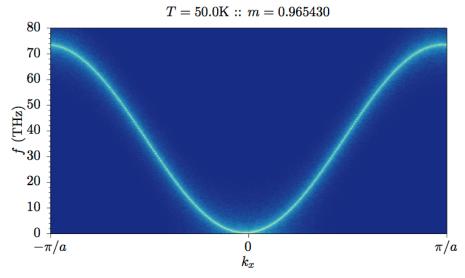


FIG. S2: Example of the spectrum calculated for a thin film using atomistic spin dynamics

To calculate the change in exchange stiffness and DMI, we fit the spin excitation spectrum with the linear spin wave dispersion relation (see Fig. S3)

$$\omega(\mathbf{k}) = \gamma_0 \left(H + \nu \left(T \right) \frac{4J}{m} \left(1 - g_k \right) + \zeta \left(T \right) \frac{2d}{m} k_x g_k \right)$$
 (S6)

where $m(T) = M_s(T)/M_s(0)$ is the reduced magnetization (M_s is the saturation magnetization), $g_k = (\cos ak_x + \cos ak_y)/2$ for the 2D simple cubic lattice. v(T) and $\zeta(T)$ describe the effective temperature dependence A(T)/A(0), and D(T)/D(0), respectively.

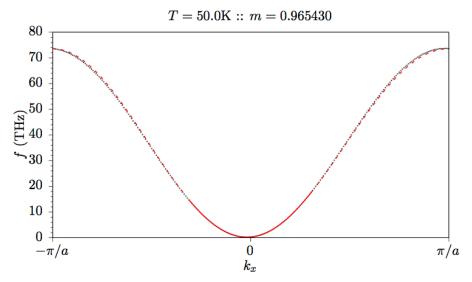


FIG: S3: Example of fitting of the linear spin wave dispersion relation. The dotted line is from the simulated data extracted by fitting a Lorentzian curve to the frequency data of each k-point. The red line is the fitted linear spin wave theory Eq. (6). The solid line indicates the long wavelength fitted region and the dash line is the continuation of the curve which is not fitted.

The scaling laws are then found by fitting the relations (see Fig. S4)

$$\frac{A(T)}{A(0)} = \left(\frac{M(T)}{M(0)}\right)^{\alpha} \qquad \frac{D(T)}{D(0)} = \left(\frac{M(T)}{M(0)}\right)^{\beta} \tag{S7}$$

giving the exponents α =1.498 +/- 0.001 and DMI β =1.495 +/- 0.007. These results depend on the lattice structure and generally are material-specific. Since the micromagnetic simulations are conducted on a square lattice, the bulk scaling exponent α is expected to be approximatively 1.6 [6]. In addition, our results are consistent with literature [6,7]. In particular, concerning the temperature dependence of the DMI parameter, in Ref. [7] the Green's function method (GF) was used. Both the ASD (our work) and GF provide access to the spin wave spectrum. In ASD this is computed in a bruteforce manner where fluctuations around the equilibrium are space-time Fourier transformed. In the GF one makes a magnon ansatz within the linear spin wave theory and solves the thermodynamics using (classical) occupation statistics with an assumption about the higher-order spin-spin correlators. The ASD is free of such assumptions. In the low temperature limit — where magnon-magnon interactions are small (usually up to 0.5 T_c) — the GF and ASD methods normally give fairly good agreement. However, the ASD is devoid of assumptions about the magnons, is valid at any temperature and ultimately should be the most accurate.

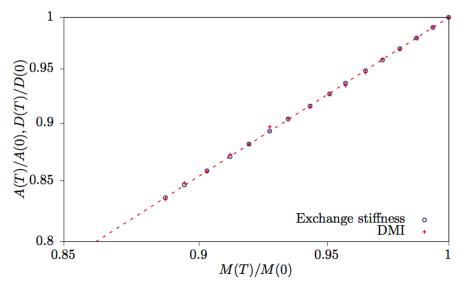


FIG: S4: Fitted scaling for the exchange stiffness A (α =1.498 +/- 0.001) and DMI strength D (β =1.495 +/- 0.007)

The micromagnetic computations are carried out by means of a state-of-the-art micromagnetic solver which numerically integrates the Landau-Lifshitz-Gilbert (LLG) equation by applying the time solver scheme Adams-Bashforth [8]:

$$\left(1 + \alpha_G^2\right) \frac{d\mathbf{m}}{d\tau} = -\left(\mathbf{m} \times \mathbf{h}_{\text{eff}}\right) - \alpha_G \mathbf{m} \times \left(\mathbf{m} \times \mathbf{h}_{\text{eff}}\right), \tag{S8}$$

where α_G is the Gilbert damping, $\mathbf{m} = \mathbf{M} / M_s$ is the normalized (reduced) magnetization, and $\tau = \gamma_0 M_s t$ is the dimensionless time, with γ_0 being the gyromagnetic ratio, and M_s the saturation magnetization. \mathbf{h}_{eff} is the normalized effective magnetic field, which includes the exchange, magnetostatic, anisotropy and external fields, as well as the interfacial DMI and the thermal field. The interfacial DMI contribution \mathbf{h}_{DMI} is obtained from the functional derivative of the DMI energy

density
$$\varepsilon_{\text{DMI}} = D \left[m_z \nabla \cdot \mathbf{m} - (\mathbf{m} \cdot \nabla) m_z \right]$$
 under the hypothesis of thin film $\left(\frac{\partial \mathbf{m}}{\partial z} = 0 \right)$ [1,9] as

$$\mathbf{h}_{\mathrm{DMI}} = -\frac{2D}{\mu_0 M_{\mathrm{S}}} \left[\left(\nabla \cdot \mathbf{m} \right) \hat{z} - \nabla m_{\mathrm{z}} \right], \tag{S9}$$

with D being the parameter taking into account the intensity of the DMI, m_z the out-of-plane component of the normalized magnetization, μ_0 the vacuum permeability, and \hat{z} the unit vector along the out-of-plane direction. The DMI affects the boundary conditions of the ferromagnetic sample in the following way $\frac{d\mathbf{m}}{dn} = \frac{D}{2A}(\hat{z} \times \mathbf{n}) \times \mathbf{m}$, where \mathbf{n} is the unit vector normal to the edge, and A is the exchange constant.

The thermal effects are accounted in Eq. (S8) as a stochastic term \mathbf{h}_{th} added to the deterministic effective magnetic field in each computational cell $\mathbf{h}_{th} = (\chi/M_S)\sqrt{2(\alpha K_BT/\mu_0\gamma_0\Delta V\,M_s\,\Delta t)}$, with K_B being the Boltzmann constant, ΔV the volume of the computational cubic cell, Δt the simulation time step, T temperature of the sample, and χ a three-dimensional white Gaussian noise with zero mean and unit variance [10,11]. The noise is assumed to be uncorrelated for each computational cell. The discretization cell size used is $2.5 \times 2.5 \times 0.8 \text{ nm}^3$.

We nucleate a skyrmion with a negative out-of-plane core (region where $-1 \le m_z < 0$) using the method proposed in Ref. [12] and calculate the area, perimeter and diameter $2R_d = D_d$ of the skyrmion in a post-process from saved snapshots of the magnetization texture.

Figs. S5 and S6 display histograms of the statistical distribution of the skyrmion diameter and perimeter, respectively, for different external magnetic fields and temperatures. All the histograms are characterized by a Gaussian distribution, but the application of the field or reduction of the temperature significantly decrease both mean and standard deviation, as indicated in the figures.

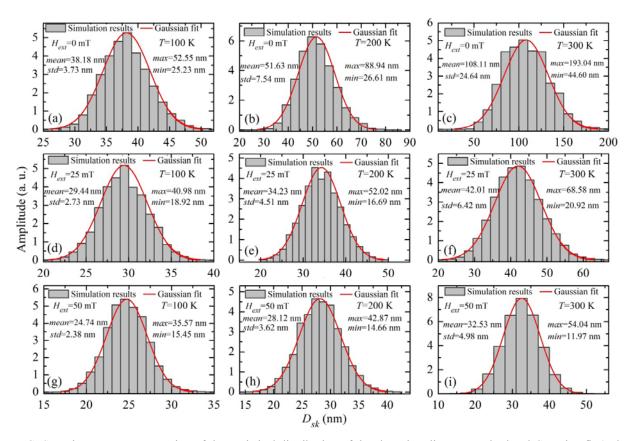


FIG. S5: Histogram representation of the statistical distribution of the skyrmion diameter and related Gaussian fit (red curve). In the rows, the external field is (a), (b), (c) H_{ext} =0 mT, (d), (e), (f) H_{ext} =25 mT, and (g), (h), (i) H_{ext} =50 mT. In the columns, the temperature is (a), (d), (g) T=100 K, (b), (e), (h) T=200 K, and (c), (f), (i) T=300 K. The notations mean, max, and min refer to the mean, maximum, and minimum values of the skyrmion diameter, while std is its standard deviation.

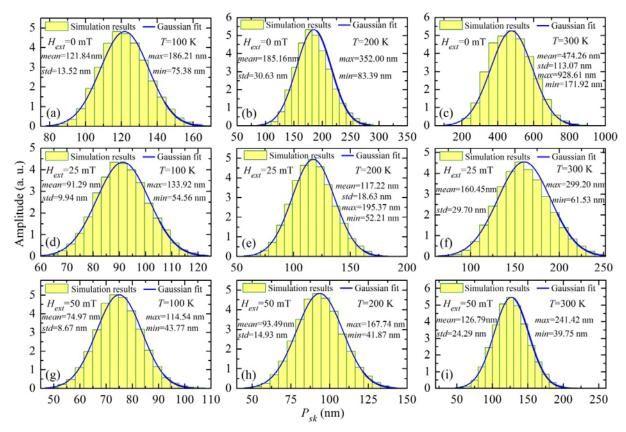


FIG. S6: Histogram representation of the statistical distribution of the skyrmion perimeter and related Gaussian fit (blue curve). In the rows, the external field is (a), (b), (c) H_{ext} =0 mT, (d), (e), (f) H_{ext} =25 mT, and (g), (h), (i) H_{ext} =50 mT. In the columns, the temperature is (a), (d), (g) T=100 K, (b), (e), (h) T=200 K, and (c), (f), (i) T=300 K. The notations mean, max, and min refer to the mean, maximum, and minimum values of the skyrmion perimeter, while std is its standard deviation.

In order to micromagnetically obtain the scaling exponent γ of the uniaxial perpendicular anisotropy, we considered γ as free parameter. We performed athermal (deterministic) micromagnetic simulations, where the thermal effect was included through the scaling relations of A(T), $K_u(T)$ and D(T) rather than including the stochastic field \mathbf{h}_{th} . As can be seen in Fig. S7(a), the best fitting has been achieved by considering γ =3.585. This γ and the temperature dependence of the saturation magnetization are the input parameters of the analytical theory.

If we consider the scaling relations as calculated from atomistic simulations, we find results in agreement with micromagnetic simulations until the skyrmion is in the metastable region far from the boundary with the ground state region (see Fig. S7(b) for T < 200 K).

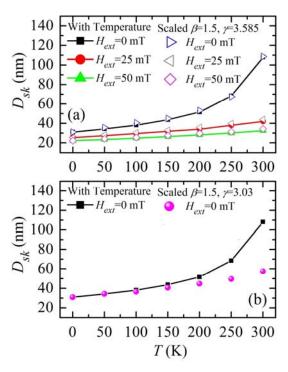


FIG. S7: Comparison between the mean value of the skyrmion diameter obtained by full micromagnetic simulations including thermal fluctuations (same as Fig. 1(b) in the main text) with the skyrmion diameter calculated from deterministic micromagnetic simulations with scaled values of the macroscopic parameters (a) α =1.5, β =1.5, γ =3.585, and (b) α =1.5, β =1.5, γ =3.03.

Fig. S8 shows a racetrack memory device where the skyrmions in the track are metastable and therefore small—giving a high storage density. The skyrmions are detected under a magnetic tunnel junction (green square) with a polarized layer with a magnetization pointing along the out-of-plane direction which generates a dipolar field parallel to the skyrmion core magnetization. This field can modify the stability properties of the skyrmion in the region below the contact, moving it through the *Q-d* phase space. By shifting the skyrmions across the line of stability, their radius will expand significantly making it much easier to detect from the tunnel magnetoresistance signal (see Supplemental Material Video 1). After leaving the detection regions, the skyrmions will return to their small size in the metastable region.

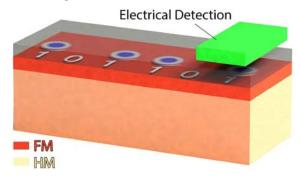


FIG. S8: Sketch of a racetrack memory device where the skyrmions (bit '1') are electrically detected below an MTJ (green square).

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